

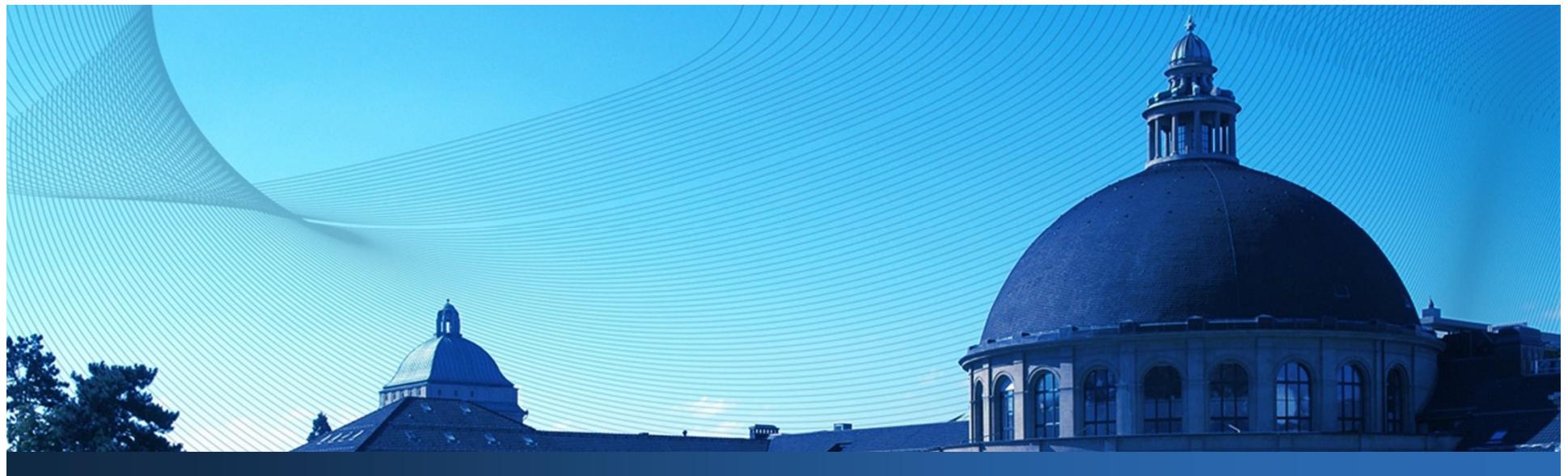


Eidgenössische Technische Hochschule Zürich
Swiss Federal Institute of Technology Zurich

The use of FEM tools for the design, control and optimization of high-speed electrical drives

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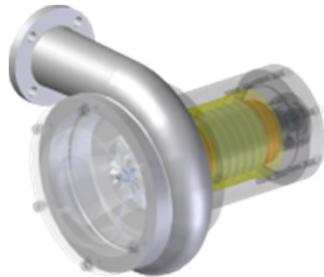
Outline

- ▶ **Ultra-high-speed drive systems**
 - ▶ Applications
 - ▶ Machine design
 - ▶ Drive strategies
- ▶ **Lateral stator machine**
 - ▶ Applications
 - ▶ Modeling and optimization
 - ▶ Active torque ripple compensation
- ▶ **Airborne wind turbines**
- ▶ **Conclusions**



Ultra-high-speed drives →
➤ Application areas

Application areas



Turbocompressors
**(fuel cells, turbochargers,
cryogenics)**



**Heating, ventilation and
air conditioning**



**Satellite
reaction wheels**



**Surgical and dental
drills**



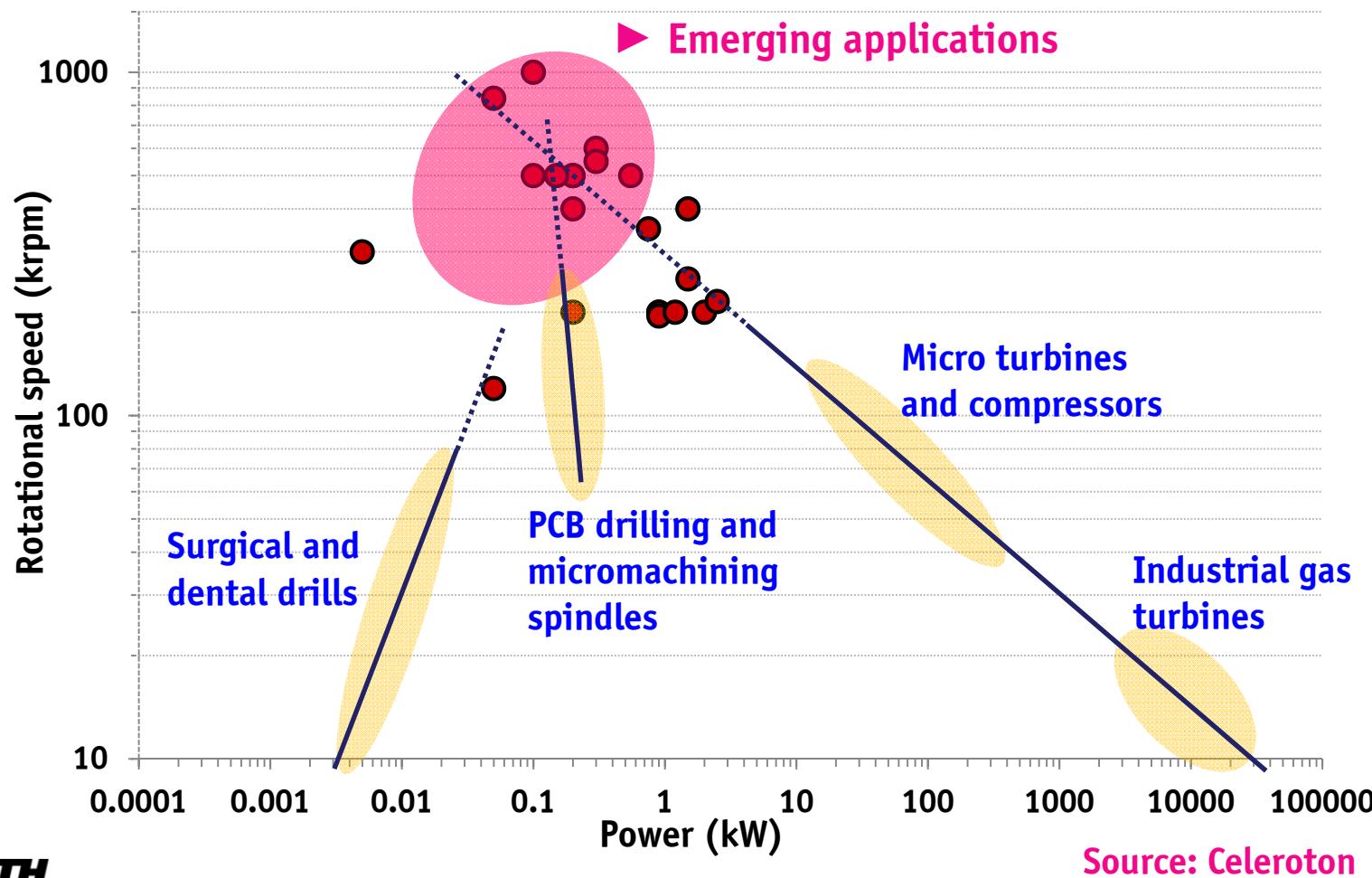
Drilling spindles



**Optical scanning
systems**

Application areas

Celeroton

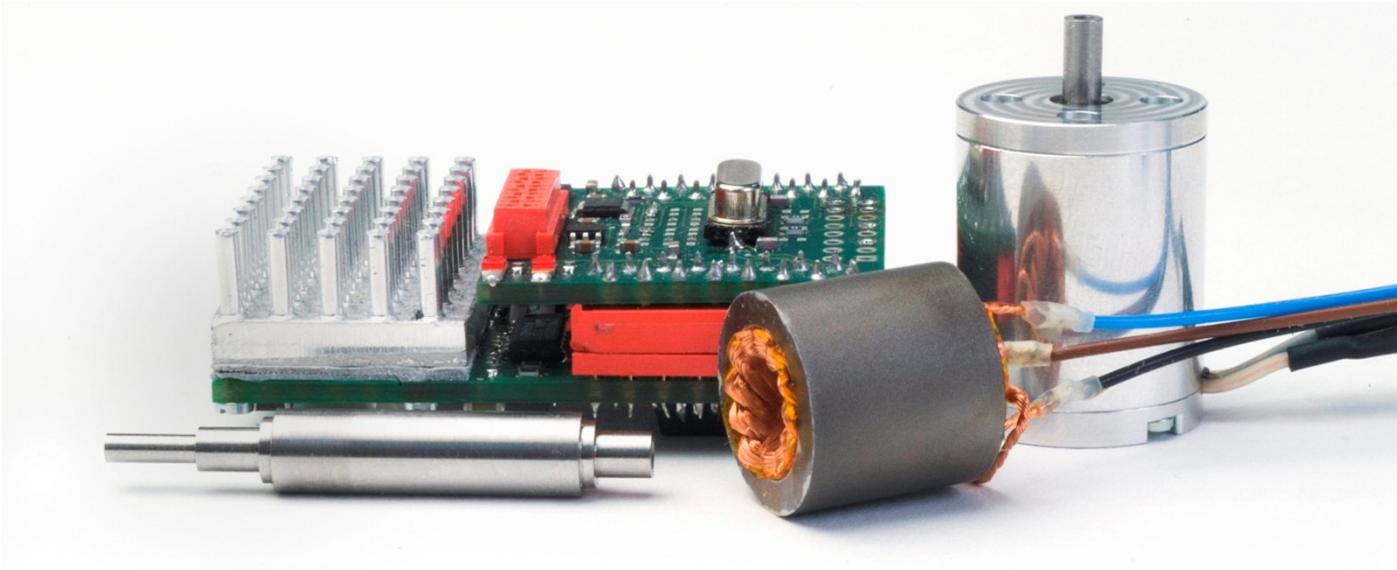


Source: Celeroton



└ Ultra-high-speed drives →
➤ Application examples

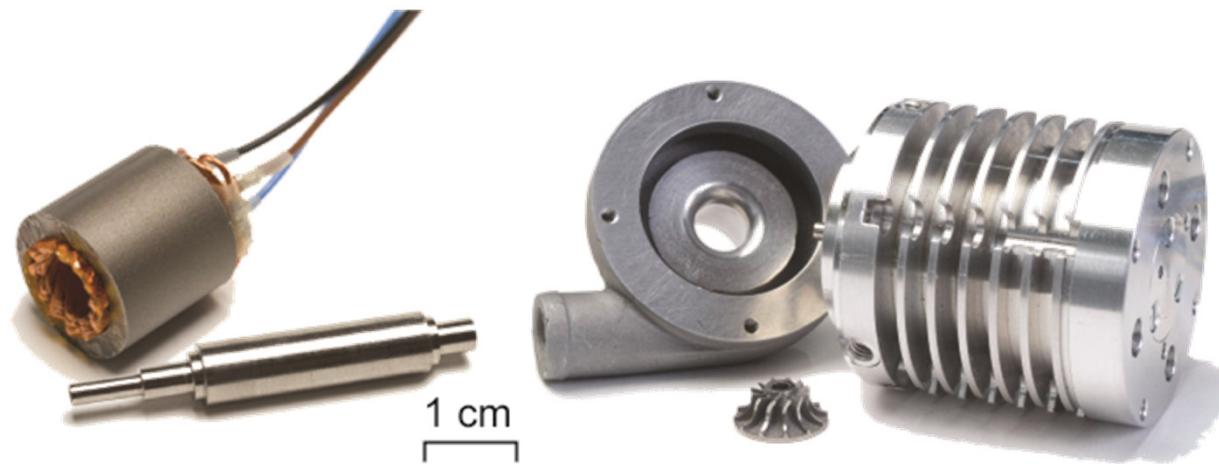
Application examples



► World Record !

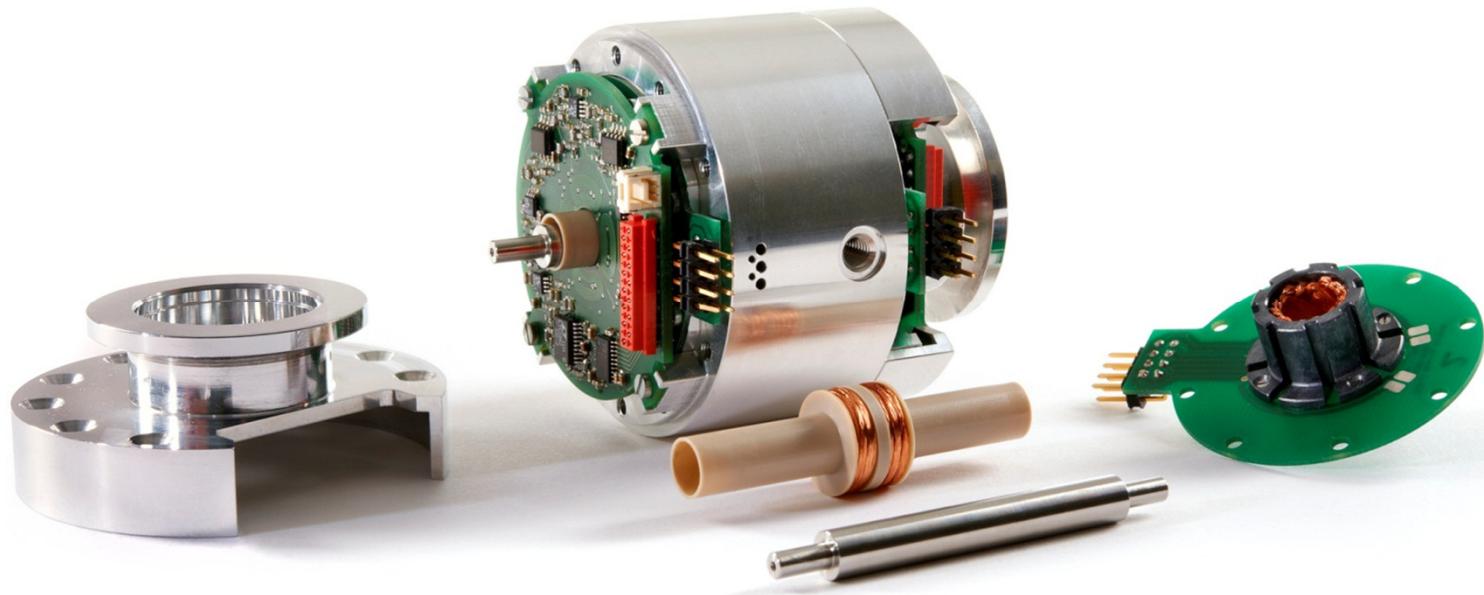
100 W @ 1'000'000 rpm

Application examples



► 500 000 rpm, 150 W Turbocompressor

Application examples



► World Record !
Magnetic bearing, 500 krpm

T. Baumgartner, J. W. Kolar, "Multivariable state feedback control of a
500 000 rpm self-bearing motor," IEEE IEMDC, 12-15 May 2013



Ultra-high-speed drives →
➤ Machine design

Slotless Motor Design

Robust and simple rotor geometry

- ▶ One-piece cylindrical magnet
- ▶ Retaining titanium sleeve
- ▶ Interference fit

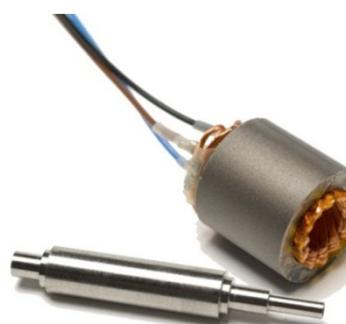
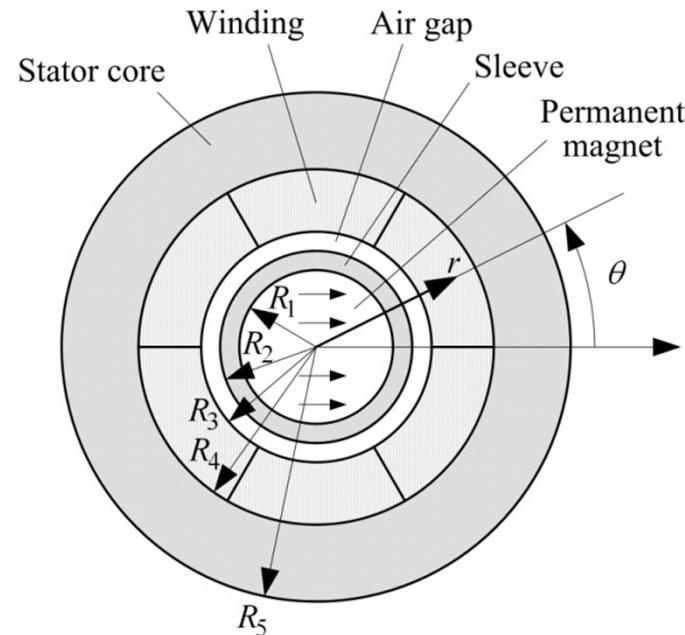
Lowest fundamental frequency

- ▶ 2 pole rotor
- ▶ 500 000 rpm \rightarrow 8.3 kHz

Low stator losses and simple construction

- ▶ 3-phase slotless litz wire winding
- ▶ Amorphous iron stator core

Low rotor losses low current reaction



C. Zwyssig, J. W. Kolar, S. D. Round, "Megaspeed Drive Systems: Pushing Beyond 1 Million r/min," IEEE/ASME Trans. on Mechatr., vol.14, no.5, Oct. 2009

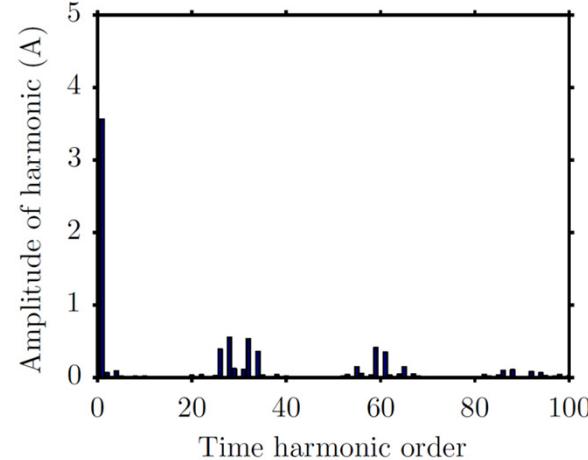
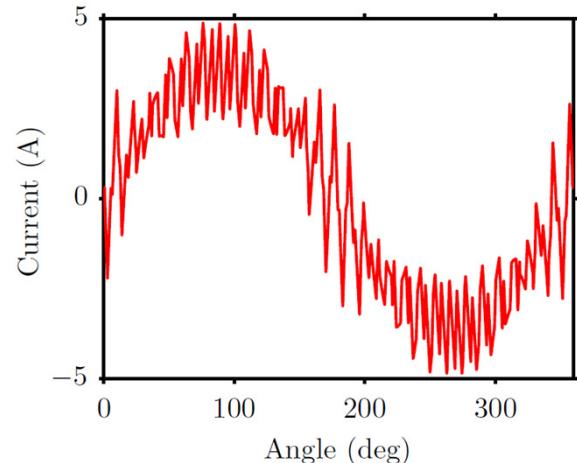
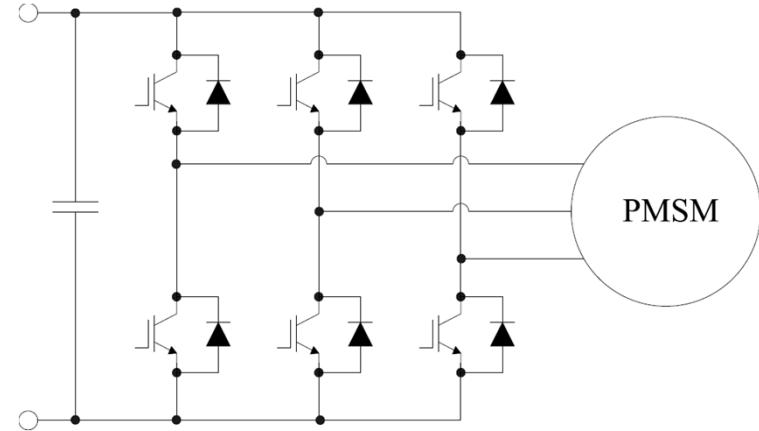


└── **Ultra-high-speed drives** →
 ➤ **Drive strategies**

Drive strategies

Pulse-Width-Modulation (PWM)

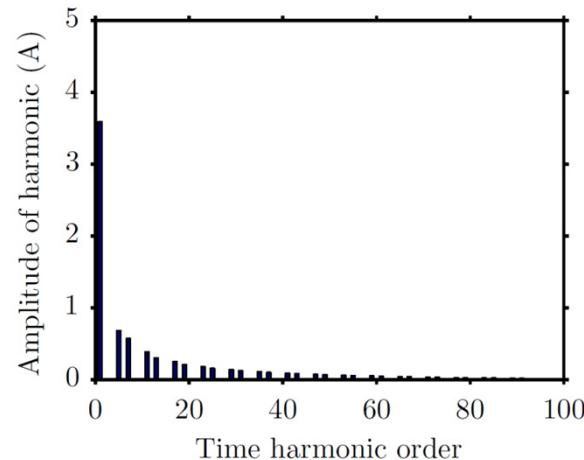
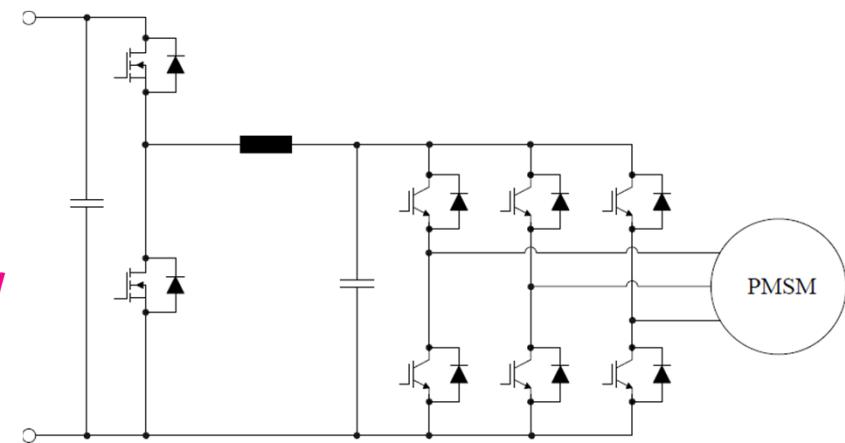
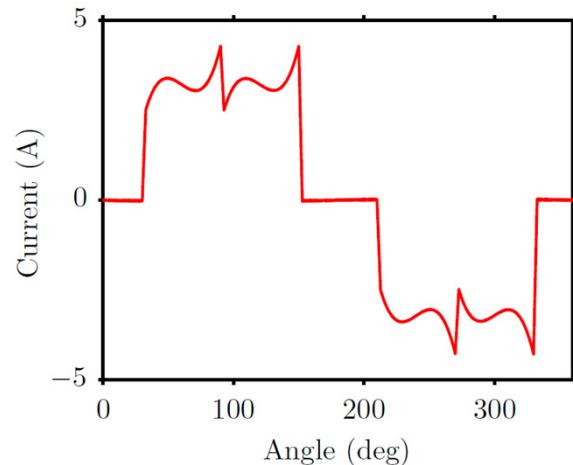
- ▶ Only three-phase inverter
- ▶ Switching frequency > fundamental frequency
- ▶ High switching losses
- ▶ High current control bandwidth requirement



Drive strategies

Pulse-Amplitude-Modulation (PAM)

- ▶ Buck converter + three-phase inverter
- ▶ Inverter switches at fundamental frequency
- ▶ Low switching losses
- ▶ DC current control



PAM or PWM, which one to use, and when?

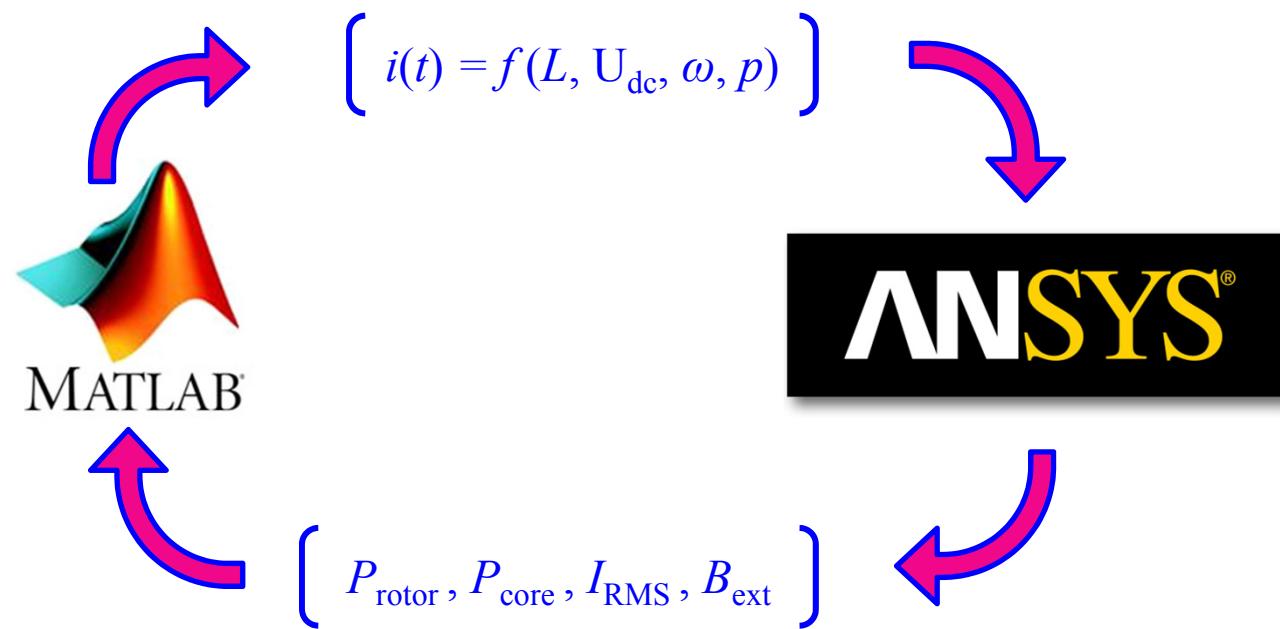
- ▶ PAM is typically used for speed above 200 krpm
- ▶ PWM is the typical industry solution up to 50 krpm

... but ...

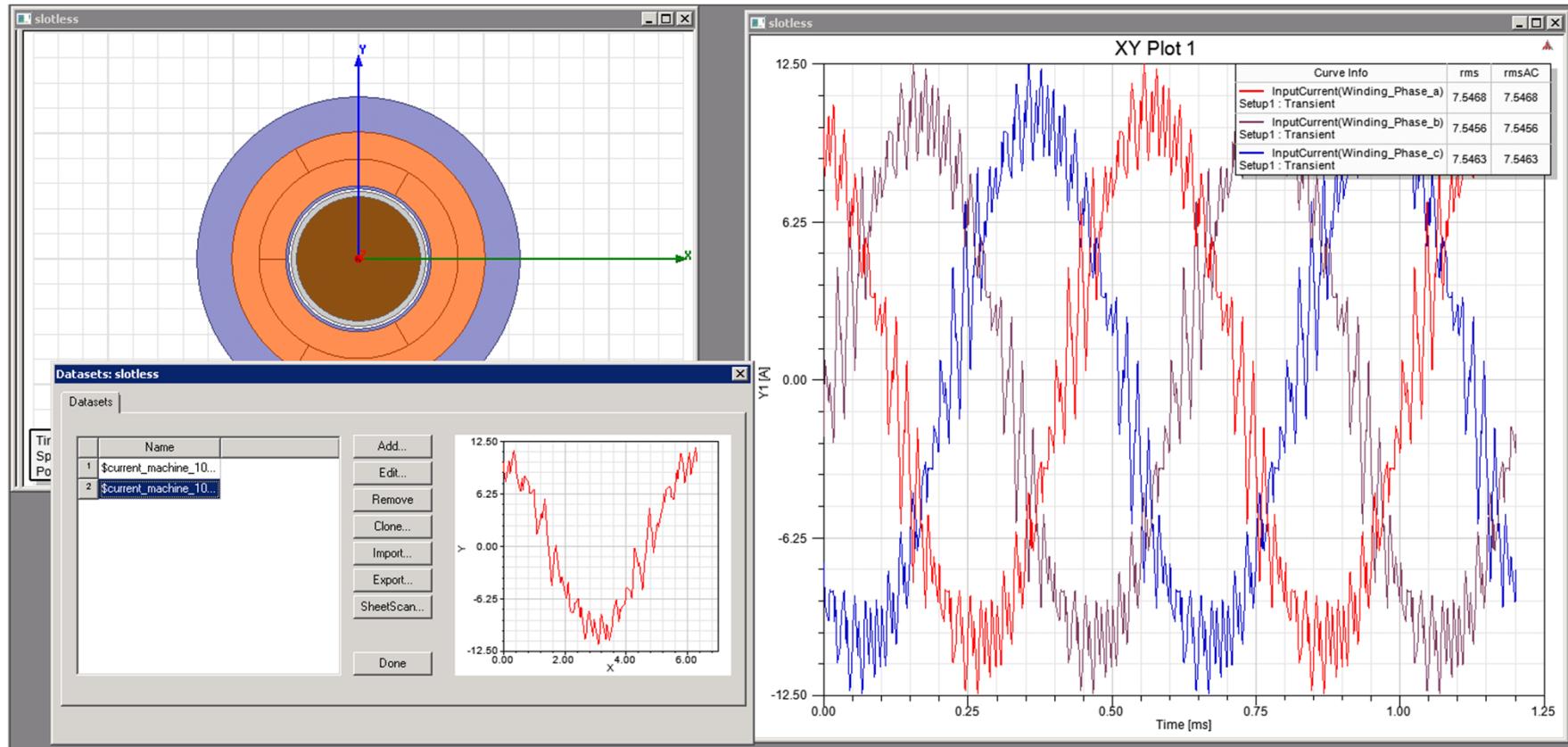
- ▶ What about between 50 – 200 krpm?
- ▶ How do PAM and PWM effect the drive system efficiency?
 - ▶ Machine losses?
 - ▶ Inverter losses?
- ▶ Do wide-band-gap (SiC, GaN) power switches change the game?

Modeling the **current shape dependent** machine losses

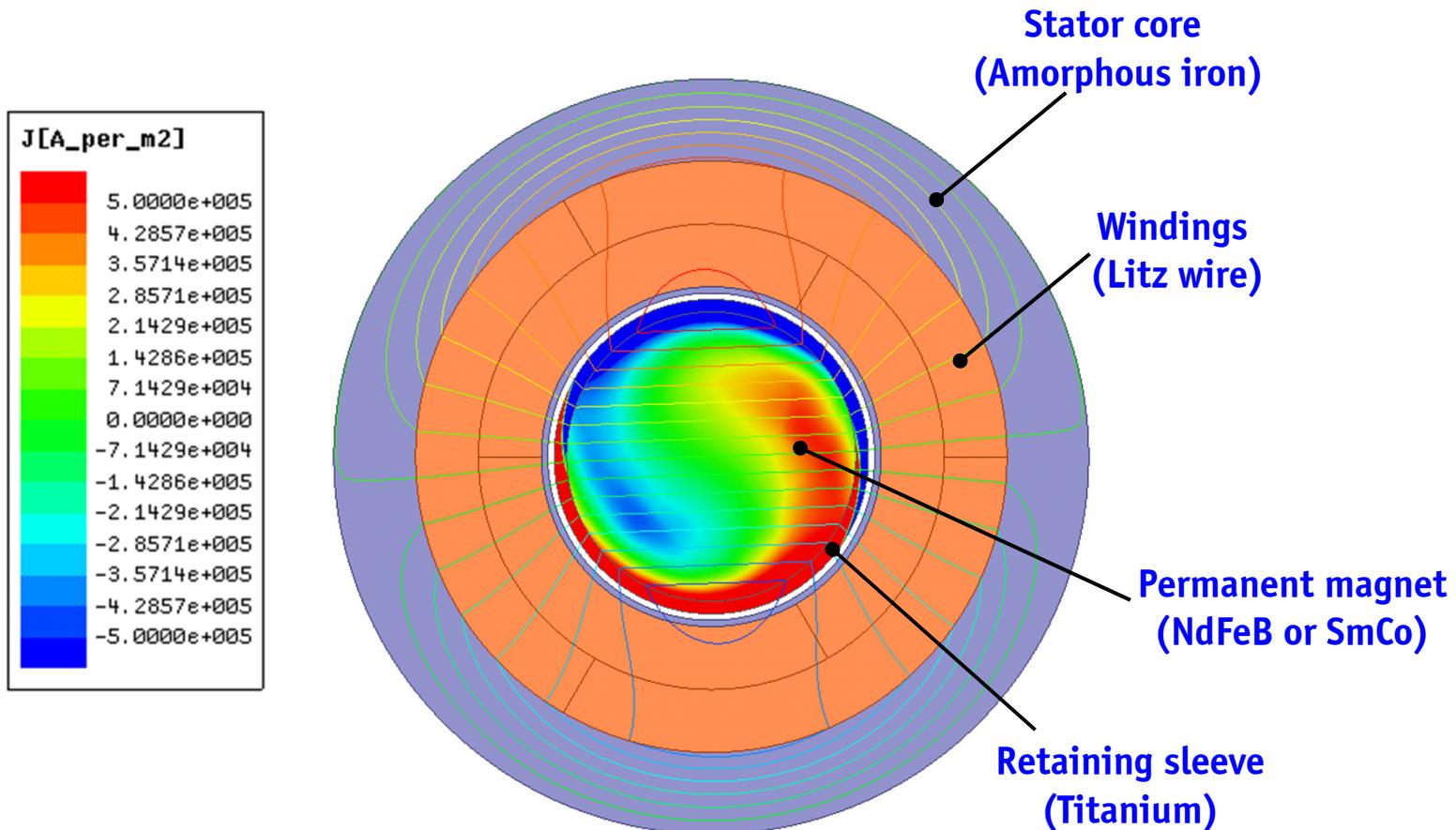
- ▶ Rotor eddy current losses
 - ▶ eddy effects, 2D
- ▶ Stator core losses
 - ▶ time domain formulation
- ▶ Copper losses (incl. skin and proximity effects)
 - ▶ RMS calculation
 - ▶ External field for proximity effect



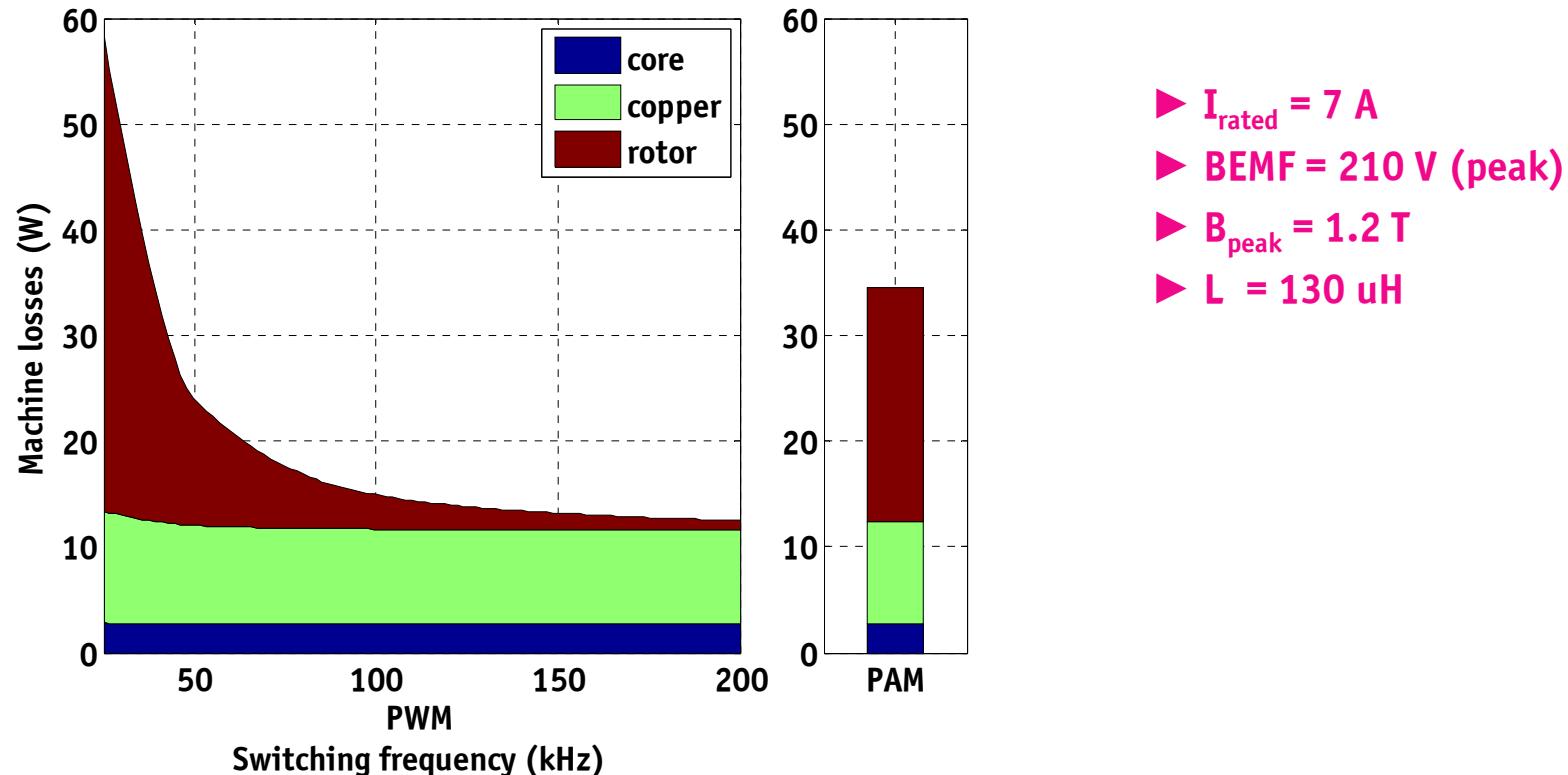
Modeling the current shape dependent machine losses



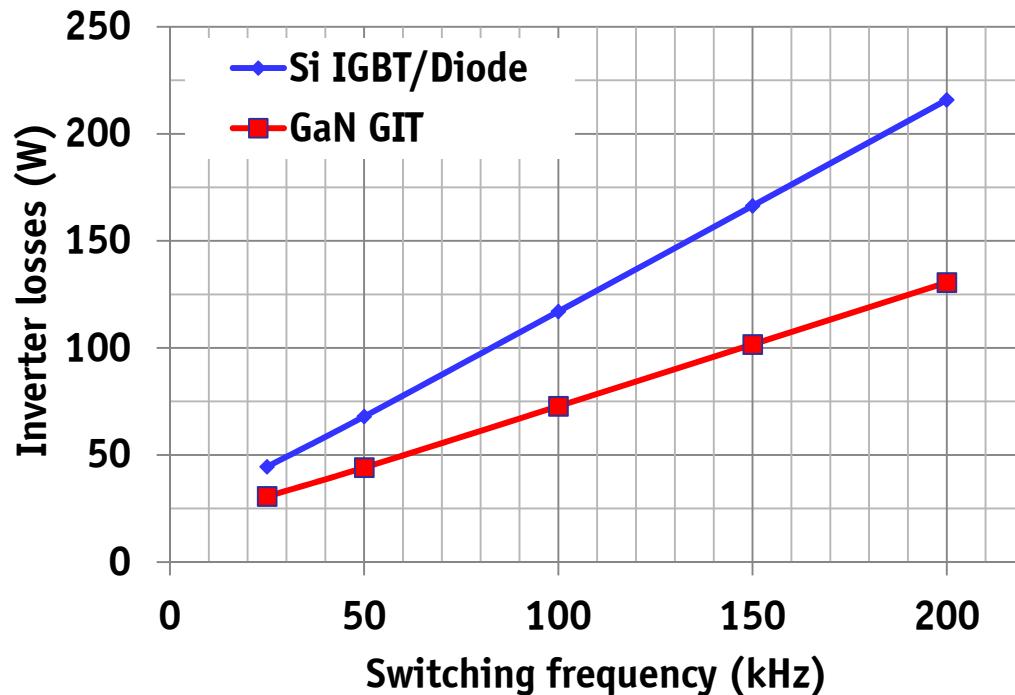
Rotor eddy current losses



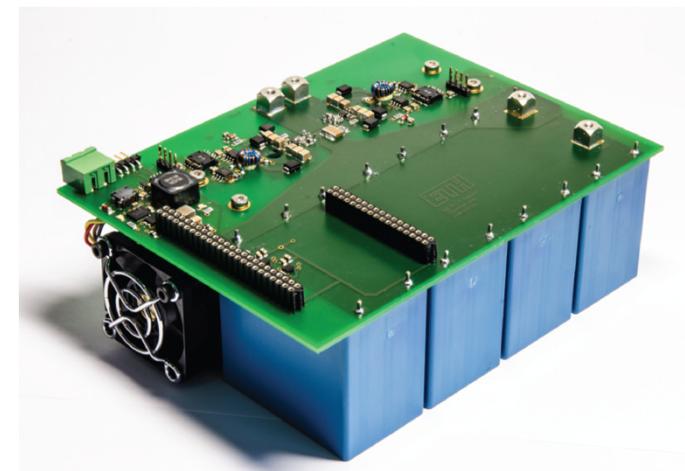
Case study: 100,000 rpm, 3 kW machine



Modeling the inverter losses



- ▶ 600 V, 15 A GaN GIT
- ▶ 600 V, 15 A Si IGBT with antiparallel diode



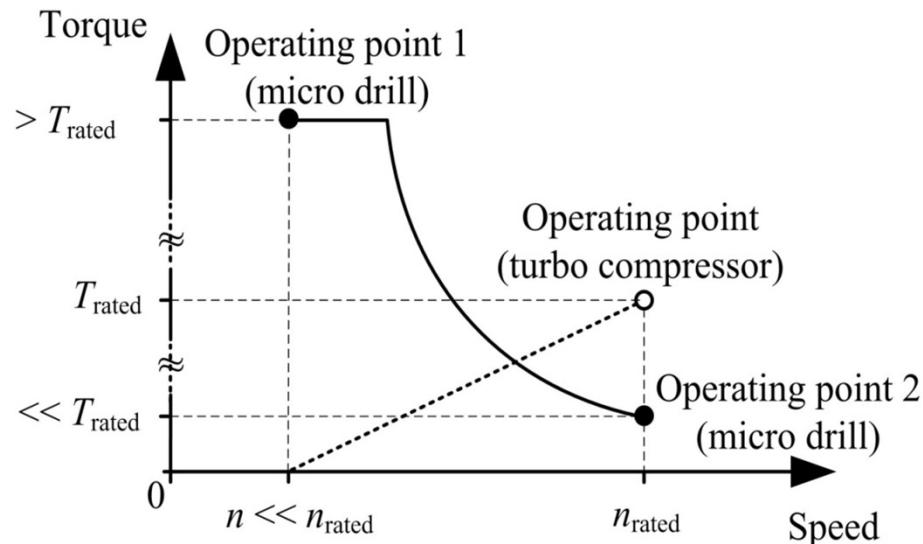
A. Tüysüz, R. Bosshard, J. W. Kolar, "Performance Comparison of a GaN GIT and a Si IGBT for High-Speed Drive Applications", IEEE ECCE Asia (IPEC), May 18-21, 2014

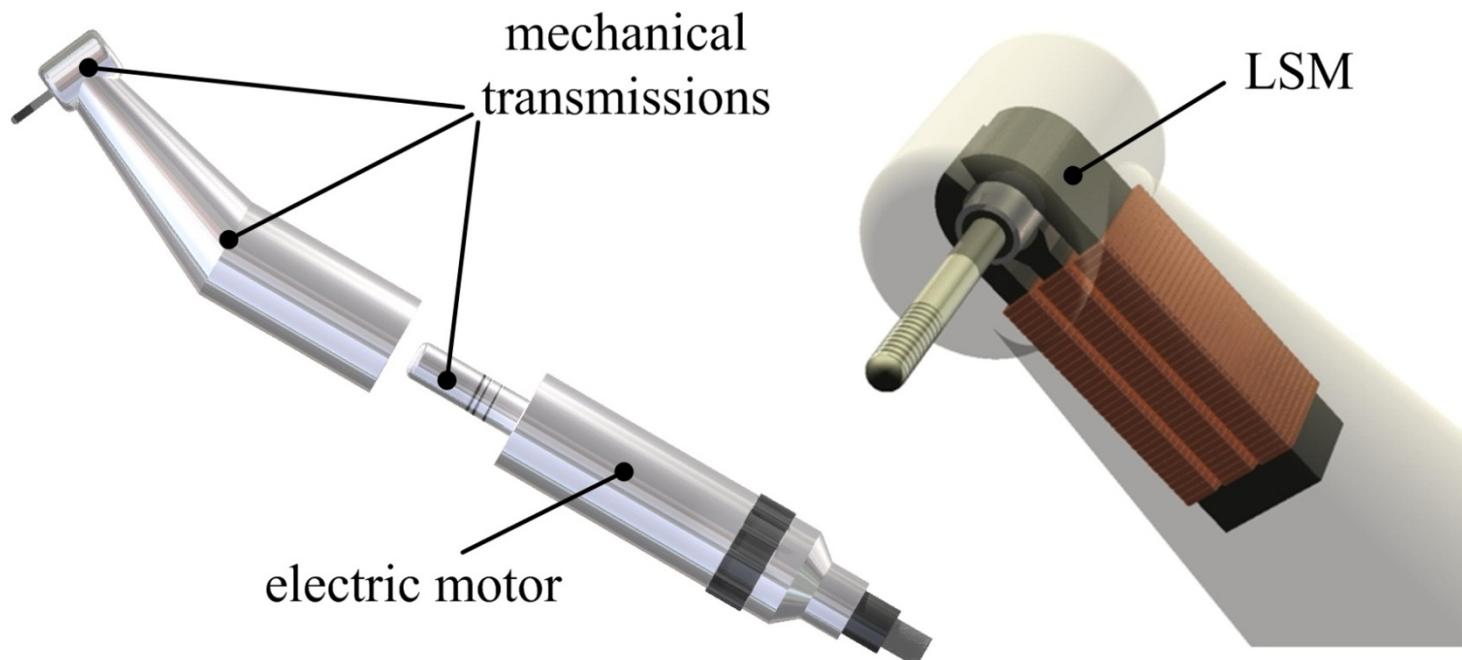


Novel Machine Topologies →
➤ Lateral stator machine

Requirements of different high-speed applications

- ▶ **Turbocompressors: Single operating point**
- ▶ **Drills – spindles: wide torque-speed range**

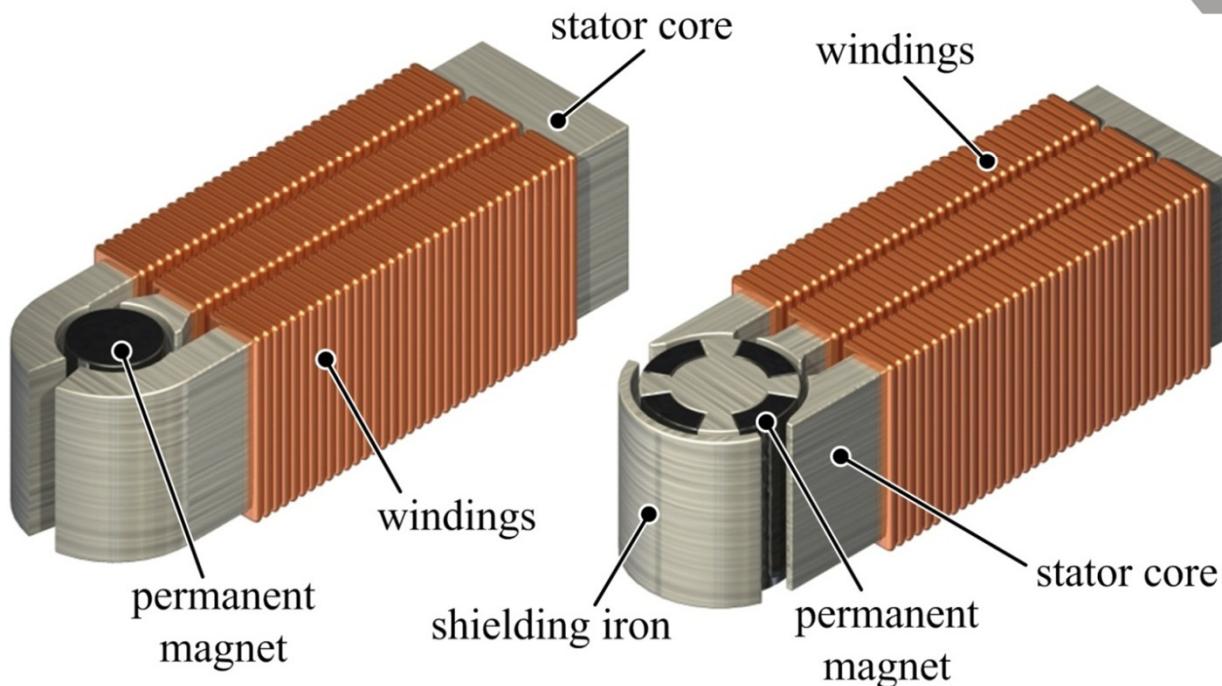
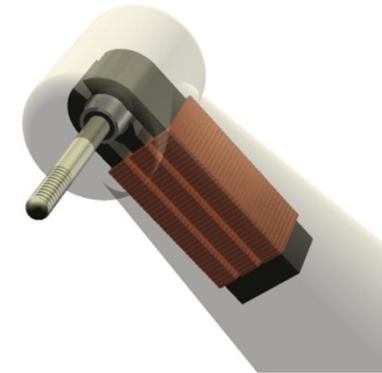




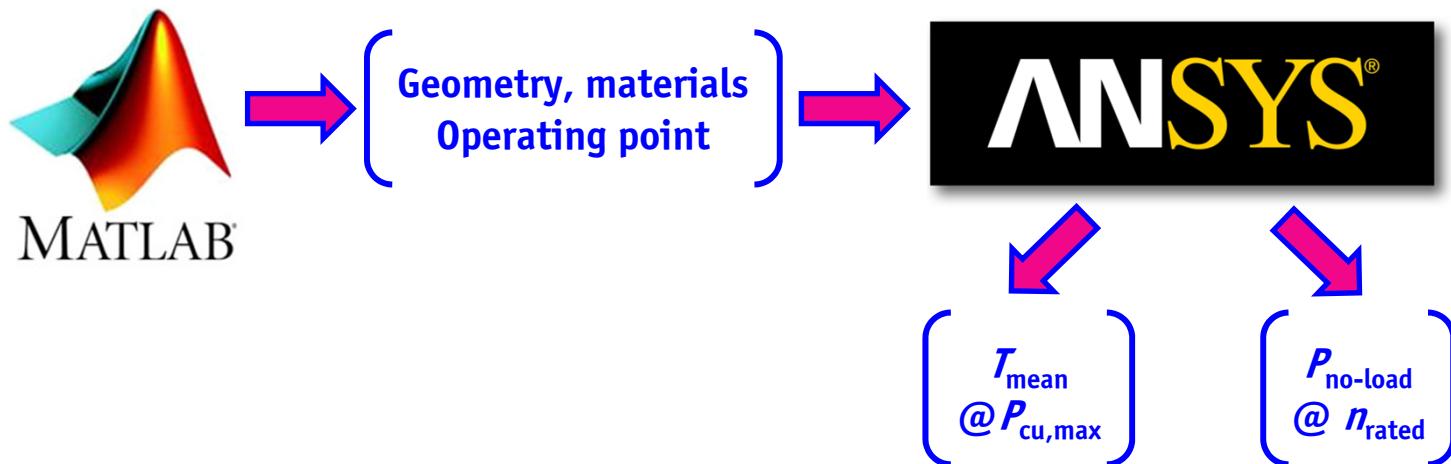
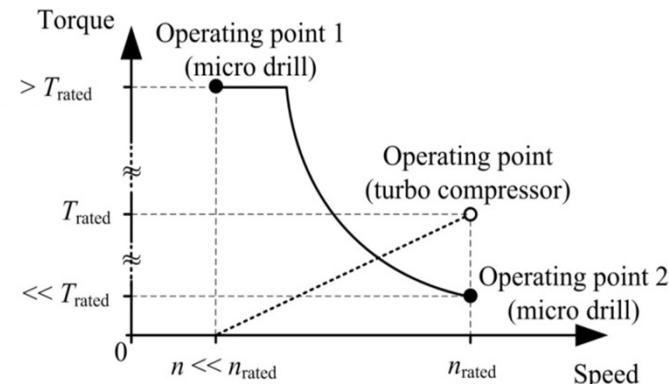
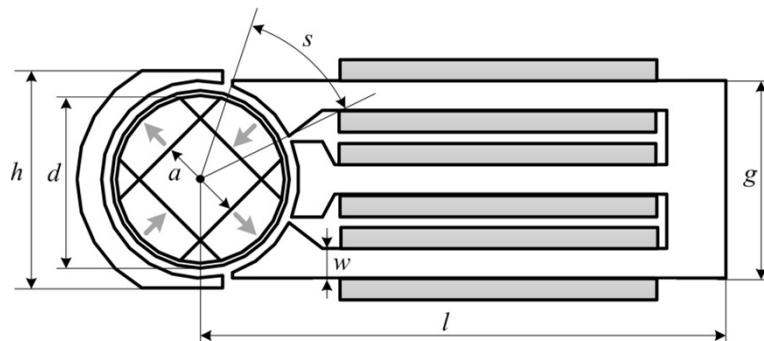
► state-of-the-art

► direct drive approach

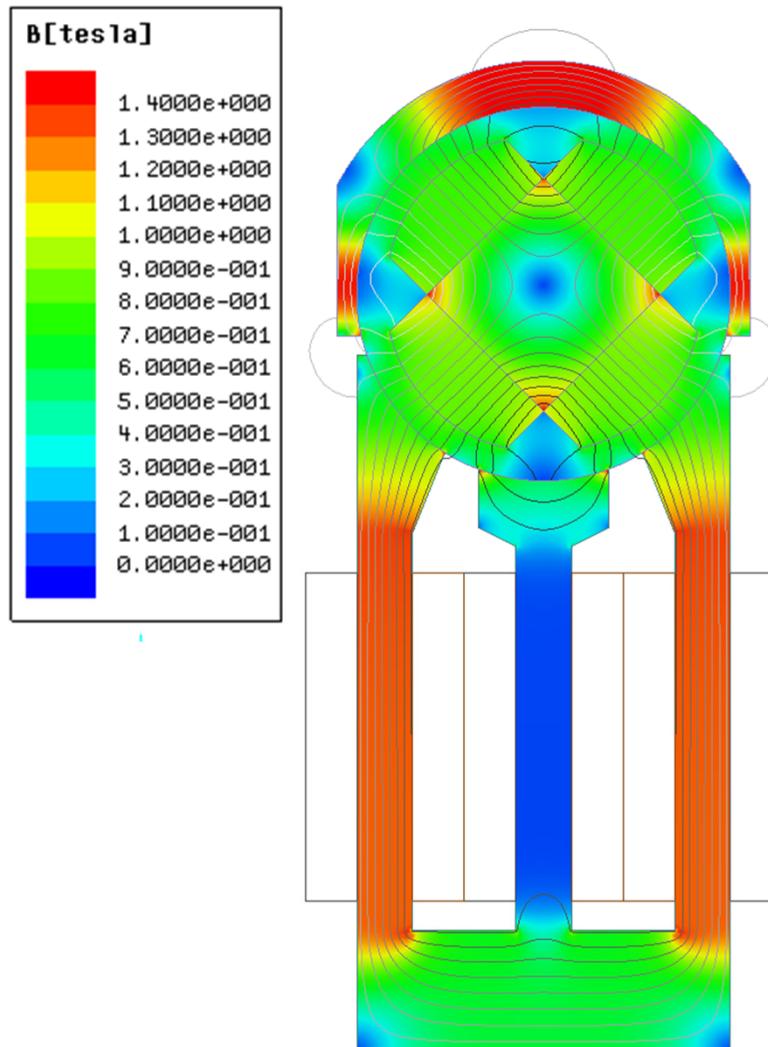
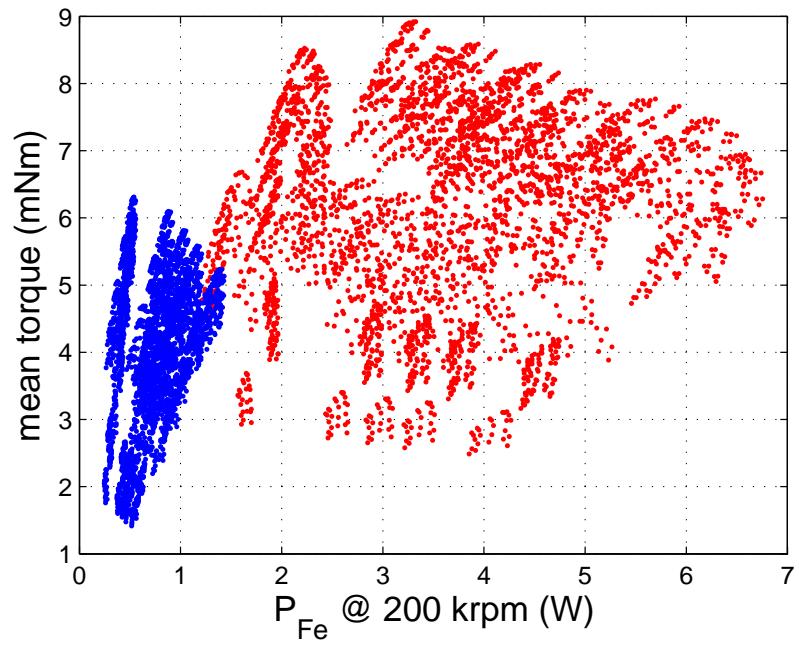
- ▶ Direct drive possible with new machine topology



Geometric parametrization

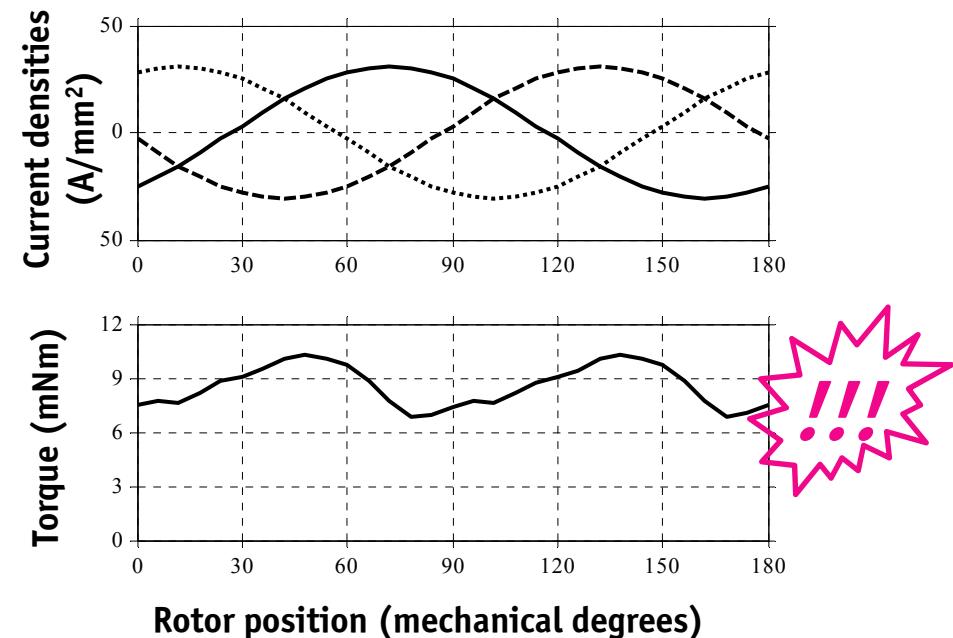
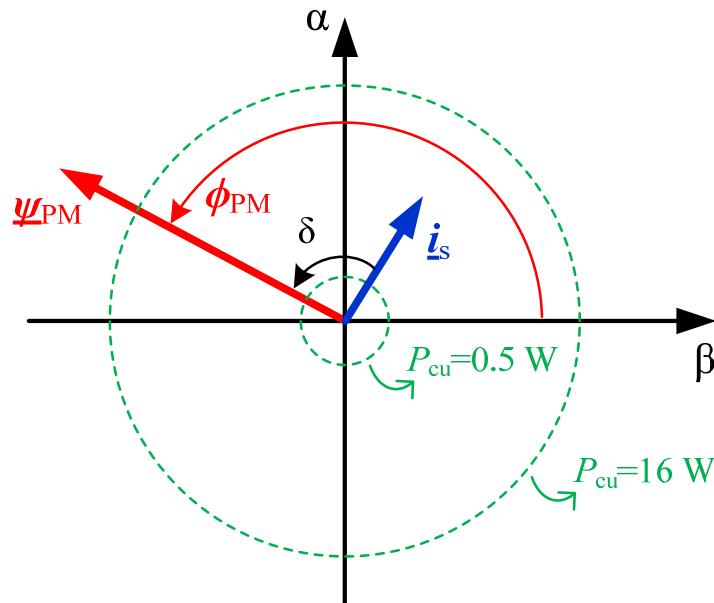


Simulation results



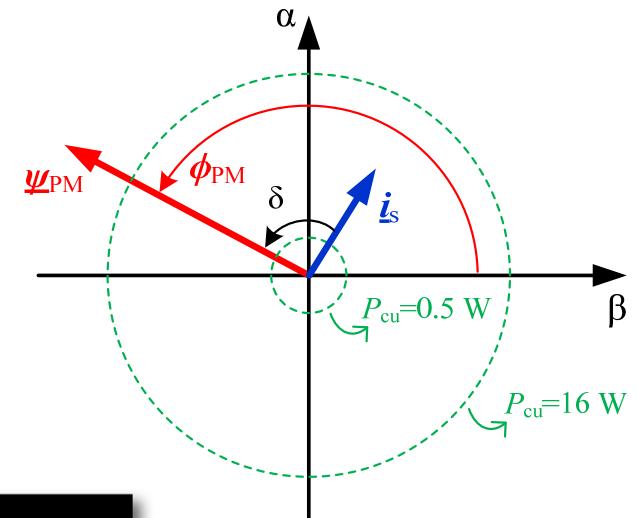
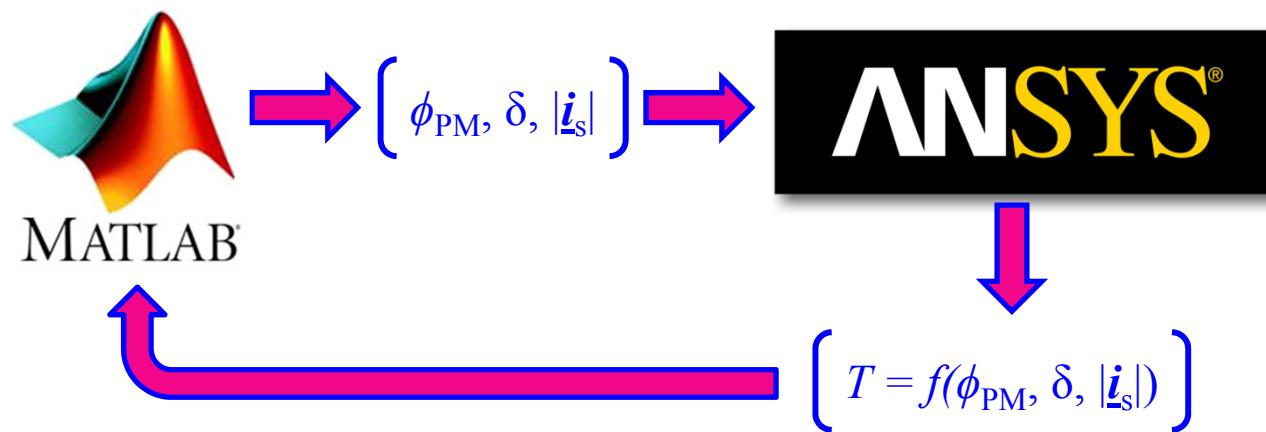
Active torque ripple compensation

- Torque ripple due to saturation, slotting, asymmetry

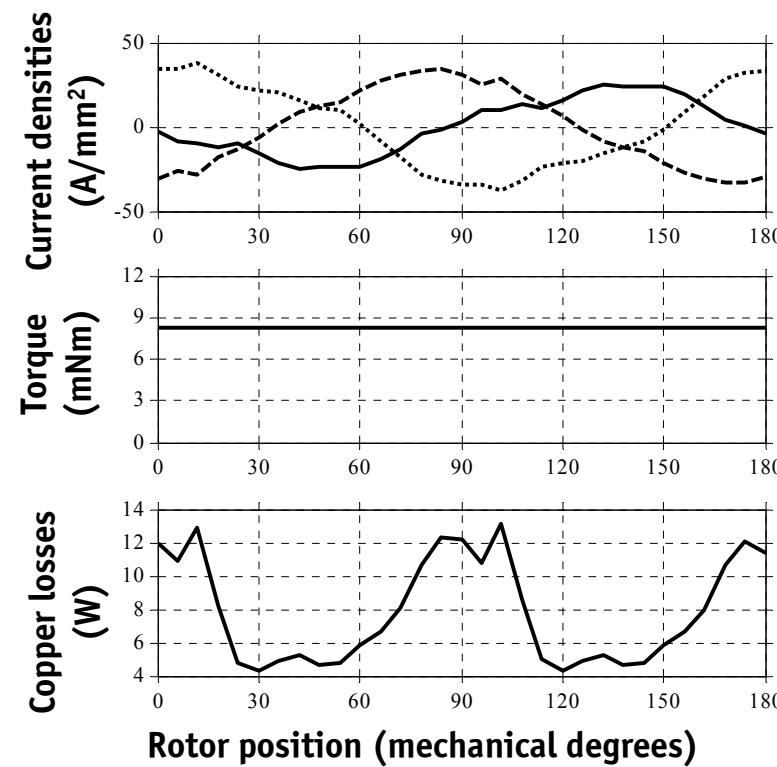
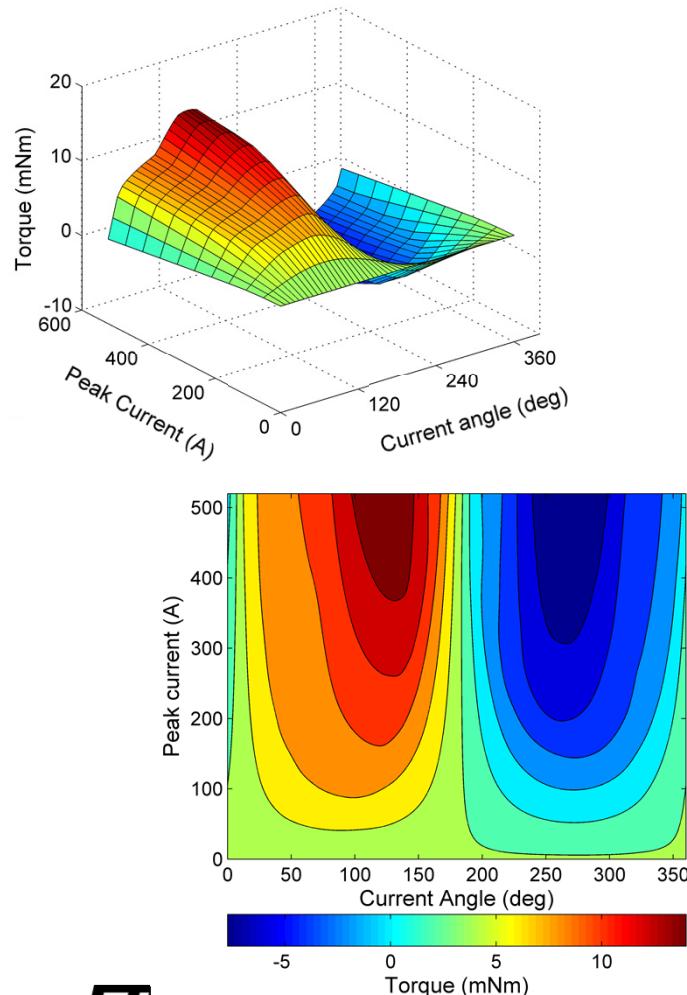


Active torque ripple compensation

- Matlab-Maxwell coupling used to calculate the optimum current profile



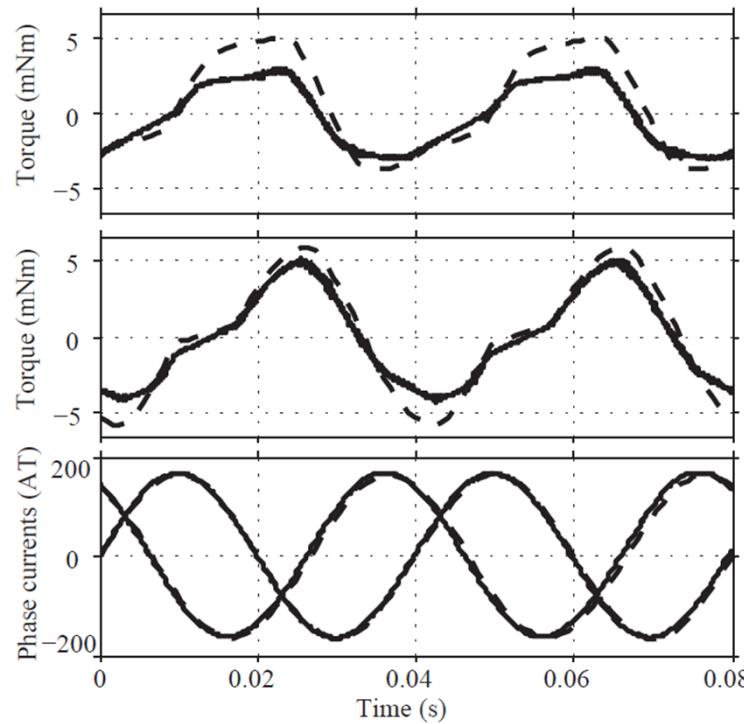
Active torque ripple compensation



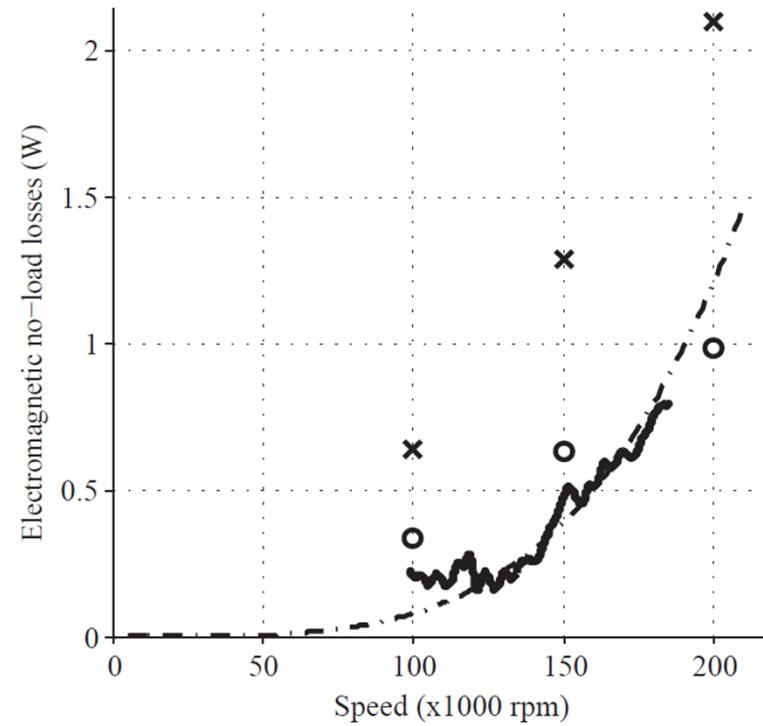
A. Tuysuz, A. Looser, J. W. Kolar, C. Zwysig, "Novel miniature motors with lateral stator for a wide torque and speed range," IEEE IECON 2010, 7-10 Nov. 2010

Accuracy of models – experimental verification

► Standstill torque measurement



► No-load loss measurement



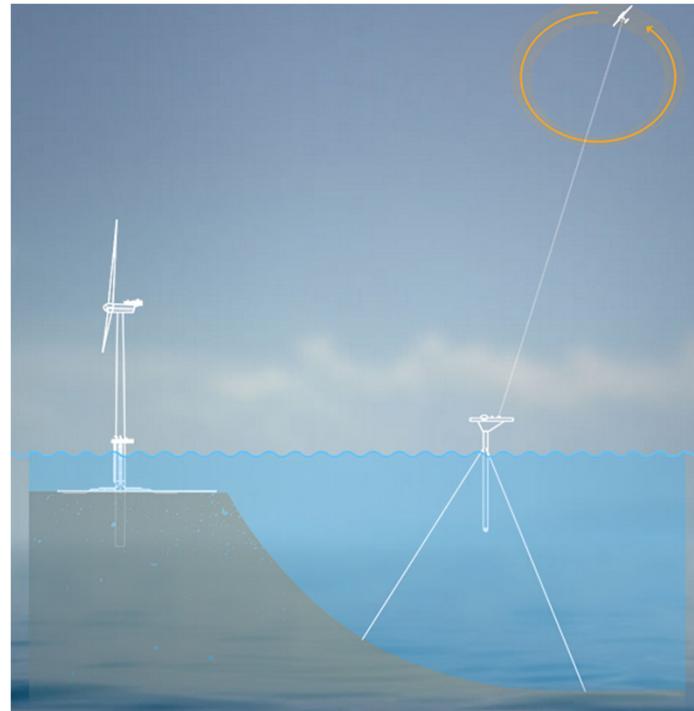
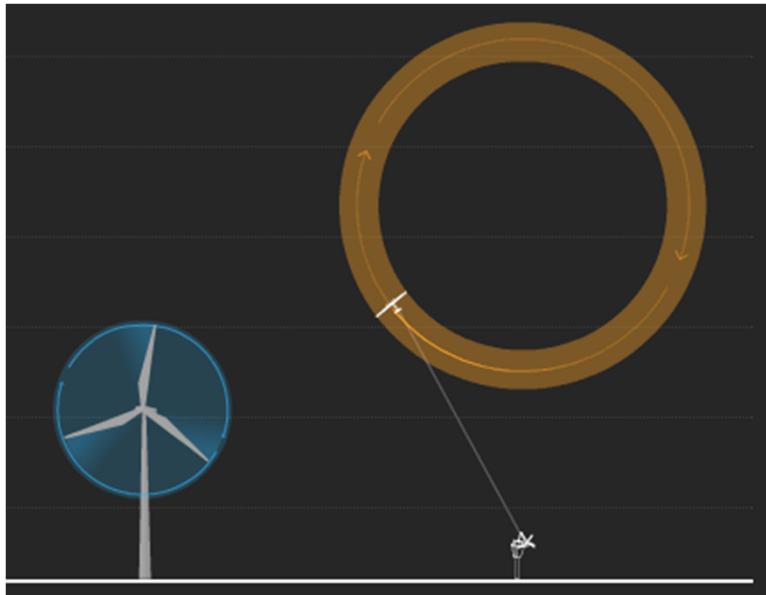


Airborne Wind Turbines

➤ Power density vs. efficiency

Airborne wind turbines

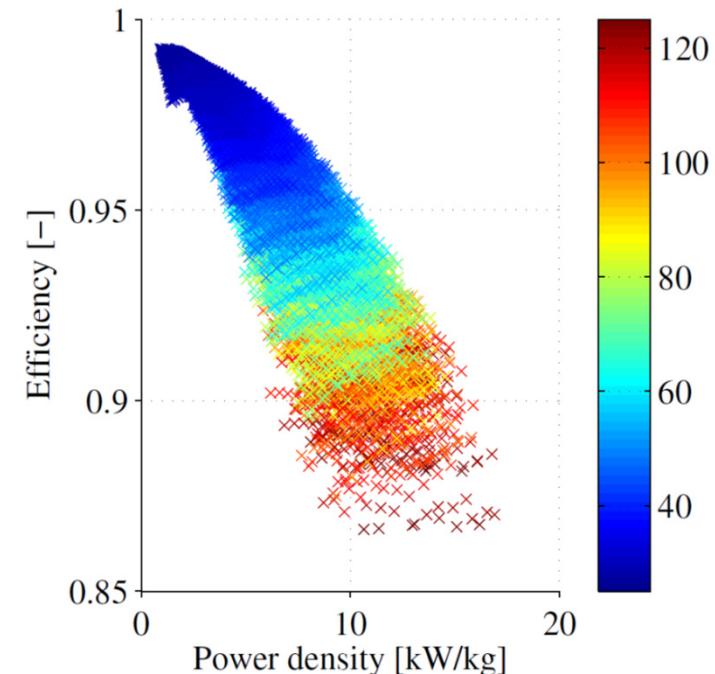
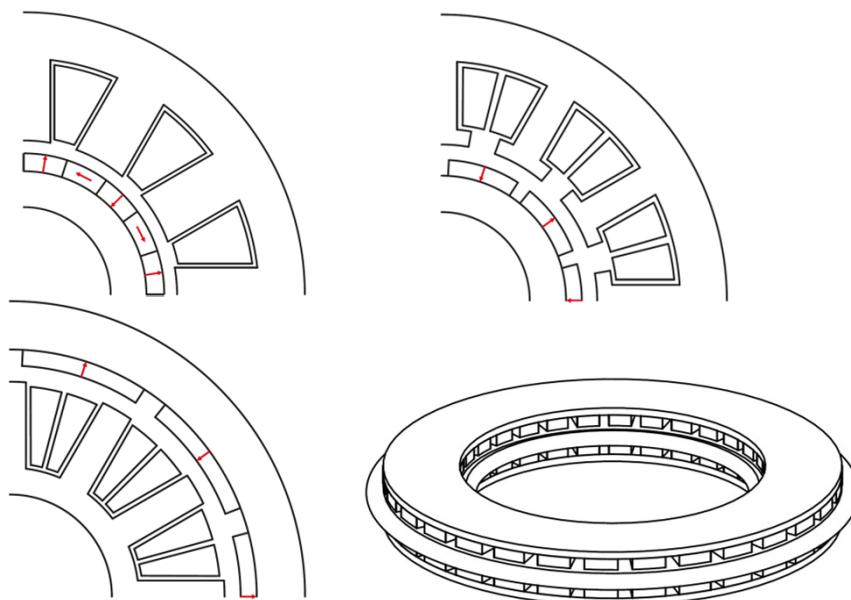
- ▶ Less material
- ▶ Cheaper
- ▶ Higher altitude winds



Source: Makani
google.com/makani/

Weight and efficiency optimized electrical machine

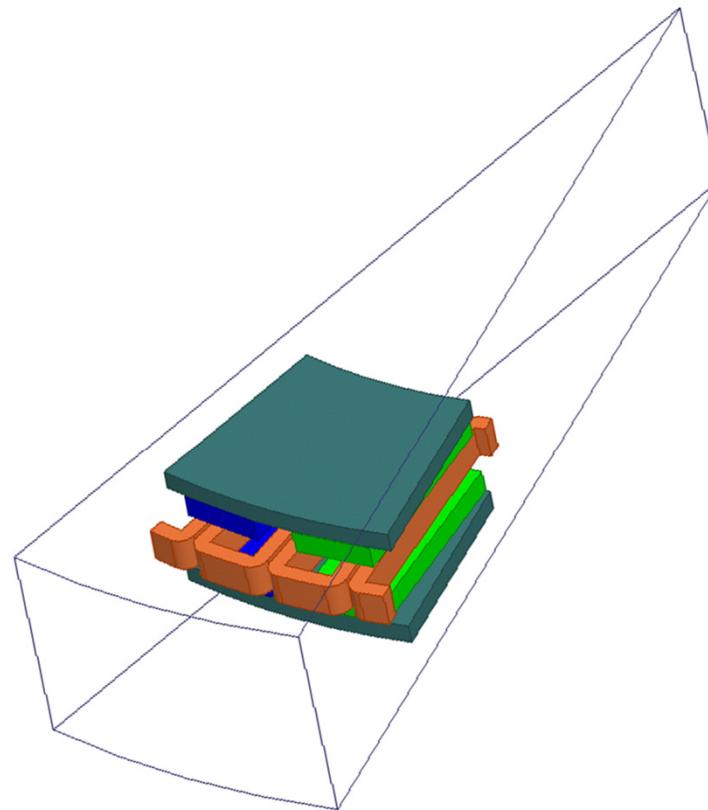
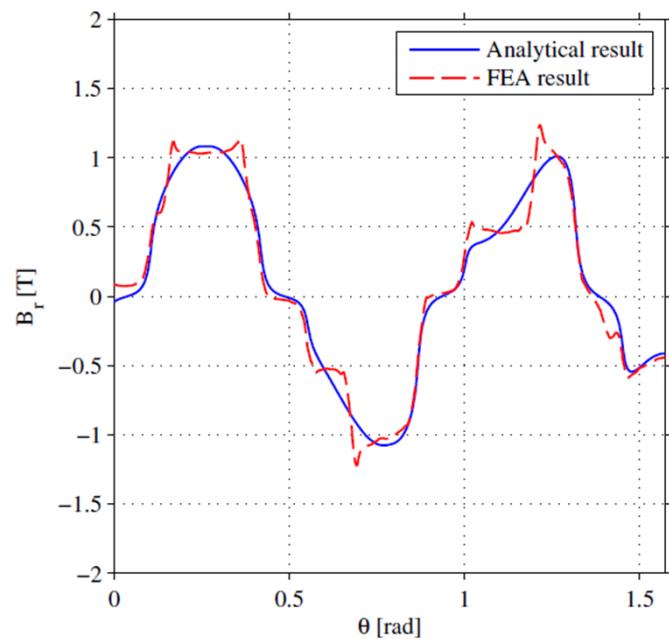
- ▶ Several different PM machine topologies
- ▶ Analytic models offer very high speeds and insight
- ▶ FEM offers high accuracy



C. Gammeter, Y. Drapela, A. Tuysuz, J. W. Kolar "Weight Optimization of a Machine for Airborne Wind Turbines," IEEE IECON 28 Oct. – 1 Nov. 2014

Weight and efficiency optimized electrical machine

- ▶ FEM is used for
 - ▶ verification of analytic models
 - ▶ fine tuning – final design





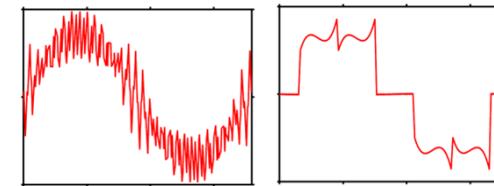
Conclusions



Conclusions

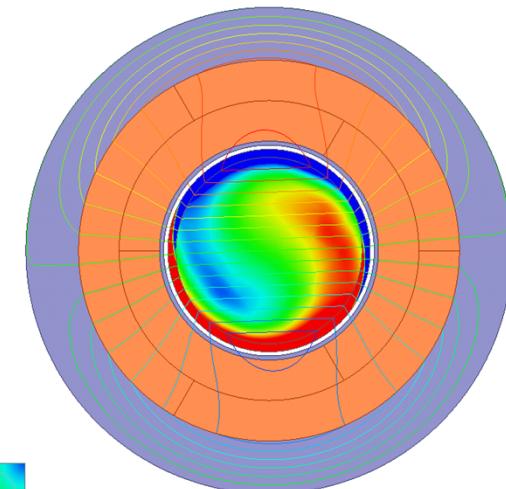
Ultra-high-speed drive systems

- ▶ Applications
- ▶ Machine – inverter interaction
- ▶ Loss models taking modulation into account



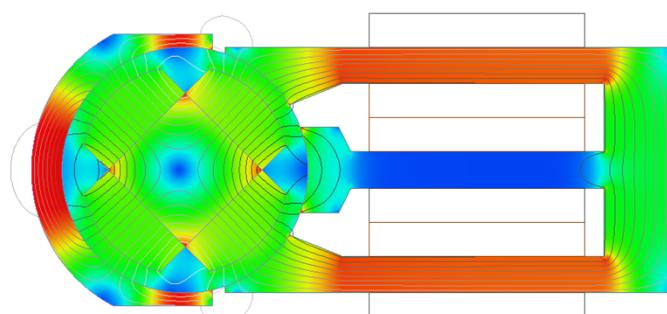
Lateral stator machine

- ▶ Geometric parameterization
- ▶ Active-torque ripple compensation



Benefits of Matlab-Maxwell coupling

Airborne wind turbines



Acknowledgement

The authors would like to thank



customer portal and support engineers



Questions ?

