



## Part 4 Experimental Analysis of 1<sup>st</sup> Gen. 600 V GaN M-BDSs

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October 10, 2021







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## The Switch: 600 V / 140 mΩ GaN M-BDS 1. Gen. Samples (infinem

#### **BDS Realization with Unipolar Devices**



▶ 4 x Single switch for same R<sub>on</sub>

### **Monolithic Bidirectional Realization (M-BDS)**



- ±600 V
- 140 mΩ
- PG-DSO-20-85
   Package

Package Image Source: https://www.infineon.com/cms/en/produ ct/packages/PG-DSO/PG-DSO-20-85/

#### **GaN M-BDS Internal Structure**

- ► Infineon 600 V CoolGaN<sup>TM</sup> Technology Normally-off (Gate Injection Transistor, GIT)
- Two gates (one per blocking direction)
- Internal common-drain configuration





Same chip region used for blocking both voltage polarities!



## The Topologies

#### GaN/SiC 3-Level T-Type AC-DC PFC Rectifier / DC-AC Inverter

#### All-GaN AC-AC Current-Source Converter









# **GaN M-BDS Gate Drive Considerations**





## **GaN Gate Injection Transistor (GIT) Gate Behavior**

Simplified MOSFET Gate Turn-On



Simplifying assumption:  $C_{gs} = const.$ 



Simplified Gate Injection Transistor (GIT) Gate Turn-On



- ► Requirements for GIT gate drive
  - Small R<sub>g</sub> for fast transients (charging/discharging of C<sub>gs</sub>)
  - Large R<sub>g</sub> during steady-state (small I<sub>Dgs</sub> of a few 10 mA)



## **Standard RRC Gate Drive Operating Principle**



**Capacitor to Decouple Transient Low-Impedance Paths** 

- **C**<sub>s</sub> >> C<sub>gs</sub> (typ.): Decoupling of High-Current Paths
- **R**<sub>ss</sub> >> R<sub>on</sub>, R<sub>off</sub>: Steady-state current (milliamperes)
- **D**<sub>1</sub>: Separate turn-on/turn-off gate resistors with HB driver

Note: **Dedicated driver ICs** with multiple outputs as alternative Note: **Bipolar supply** to ensure negative  $v_{gs}$  at all times (not just transiently; relevant for CSI commutation cells)



Assumptions:  $R_{g,int} = 0 \Omega$ ,  $C_s >> C_{gs}$ , simplified gate model ( $C_{gs} = const$ .)

Note: unipolar supply possible; bipolar supply for better robustness against parasitic turn-on in current-source converter commutation cells (see later).



## **Advanced RRC Gate Drive Operating Principle**

#### , C<sub>s</sub> discharges via $R_{off}$ , $D_1$ and $D_4$ HB Driver **RRC Adaption Network** τ ≈ R<sub>off</sub>C<sub>s</sub> **V**<sub>Cs</sub> $V_{\rm Cs,max} = V_{\rm p} - V_{\rm Dgs} - V_{\rm F}$ V<sub>p</sub> $\tau \approx R_{\rm on}C_{\rm s}$ $D_2$ $R_{g,int}$ $R_{\rm on}$ $V_{\rm s,min} = 2V_{\rm F}$ $D_4$ $R_{\rm off}$ $v_{\rm Cs}$ D<sub>2</sub> prevents further $V_{\rm n}$ $S_2$ Independent discharge via $R_{ss}$ of duty-cycle $> D_{gs}$ clamps $V_{ m Dgs}$ - $\tau \approx R_{\rm off}C_{\rm gs}$ $\tau \approx R_{\rm on}C_{\rm gs}$ D<sub>2</sub>: Prevents full discharge of C<sub>2</sub> via R<sub>2</sub> $-(V_{\rm n}+V_{\rm F})$ D<sub>3</sub>: Decouple R<sub>ss</sub> during off-state D₁ clamps • $D_{A}$ : Discharge path for $C_{s}$ during off-state (via $R_{off}$ and $D_{1}$ ) and clamping of gate to negative supply voltage $S_1$ **D**<sub>5</sub>: Prevents negative voltage across C<sub>s</sub> (e.g., due to miller current or other distortions; inactive during normal operation) $S_{2}$ Straightforward option with standard HB driver IC and a

#### **Eliminating the Duty-Cycle Dependency of Dynamics**



Further reading: D. Bortis, O. Knecht, D. Neumayr, and J. W. Kolar, "Comprehensive evaluation of GaN GIT in low- and high-frequency bridge leg applications," in *Proc. 8th IEEE Int. Power Electron. Motion Ctrl. Conf. (IPEMC-ECCE Asia)*, Hefei, China, May 2016, pp. 21–30.

few Schottky diodes





## **Advanced RRC Gate Drive for M-BDS: Realization**

- ► Two gates per M-BDS / Two isolated power supplies / Two control signals
- Mostly vertical gate loop (ca. 8...10 nH incl. package) / Adv. RRC network on TOP / HB driver supply decoupling on BOT



Remark: Integration of gate drive  $\rightarrow$  Significant reduction of PCB area!







## **Advanced RRC Gate Drive for M-BDS: Layout / Measurements**

- ► Two gates per M-BDS / Two isolated power supplies / Two control signals
- Mostly vertical gate loop (ca. 8...10 nH incl. package) / Adv. RRC network on TOP / HB driver supply decoupling on BOT



### Remark: Integration of gate drive $\rightarrow$ Significant reduction of PCB area!







## **3-Level T-Type Inverters/Rectifiers with GaN M-BDSs**



Details => Paper @ ECCE USA 2021

F. Vollmaier, N. Nain, J. Huber, J. W. Kolar, K. K. Leong, and B. Pandya, "Performance evaluation of

future T-Type PFC rectifier and inverter systems with monolithic bidirectional 600 V GaN switches."







## **3-Level T-Type (TT) Main Converter Stage**

- ▶ Bidirectional voltage-source AC-DC or DC-AC conversion / Basic building block for PFC rectifiers or motor drive inverters
- Phase-modular DC-link-referenced first LC-filter stage => DM and CM filtering



- Three-level bridge-leg via connection to DC-link midpoint: bidirectional conduction & bipolar blocking => M-BDS
- 800 V DC / S<sub>x,H</sub>, S<sub>x,L</sub>: 1200 V, 140 mΩ SiC MOSFET / S<sub>x,M</sub>: 600 V, 140 mΩ GaN M-BDS





## **3-Level TT Bridge-Leg Commutation Cells**



→ High-side commutation cell active



#### **Negative Output Voltage**

 $\rightarrow$  Low-side commutation cell active



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## **3-Level TT Bridge-Leg Evaluation Board**

- 800 V DC / S<sub>x,H</sub>, S<sub>x,L</sub>: 1200 V, 140 mΩ SiC MOSFET (IMBG120R140M1H) / S<sub>x,M</sub>: 600 V, 140 mΩ GaN M-BDS
- ▶ Two commutation loops: High-side / Low-side / Commutation inductance ca. 15 nH
- Advanced RRC gate drive with HB driver (2EDS8265HXUMA1) for M-BDS



Cooling through PCB (thermal vias) / Top-side cooled packages would facilitate improved layouts





### Continuous M-BDS Operation at ± 400 V in CCM







## **Remark: CCM and TCM Operation of TT Bridge-Leg**



800 V DC and 2 kW.





## Continuous M-BDS Operation at ± 400 V with TCM (Soft-Switching)







## **Transient Calorimetric Loss Measurement: Principle (1)**

Constant power dissipation into metal block



Step 1: Calibration with Known DC Power measurement

- Record  $\Delta T(\Delta t)$  for several (at least two) known powers
- Fit model and extract model parameters C<sub>th</sub> and R<sub>th</sub>

$$\Delta T(\Delta t) = PR_{\rm th} \cdot \left(1 - e^{-\frac{\Delta t}{R_{\rm th}C_{\rm th}}}\right)$$

### **Step 2:** Measurement of <u>Unknown</u> Power Dissipation

- Measure time  $\Delta t$  to reach temperature difference  $\Delta T$
- Use calibrated model to calculate power dissipation

$$\Rightarrow P(\Delta T, \Delta t) = \frac{\Delta T}{R_{\rm th} \cdot \left(1 - e^{-\frac{\Delta t}{R_{\rm th}C_{\rm th}}}\right)}$$

Alternative for Step 2

- Record  $\Delta T(\Delta t)$  for <u>unknown</u> power dissipation *P*'
- Fit model with known  $R_{\rm th}$  and  $C_{\rm th}$  to identify P'





## **Transient Calorimetric Loss Measurement: Principle (2)**

#### Half-Bridge with Identical Switches



Note: Heat sink size  $(C_{th})$  follows from desired temperature rise (resolution), measurement time, and power dissipation

#### Switching Loss Extraction

- Calorimetric loss meas. gives total losses
- Conduction losses can be calculated:

 $P_{\text{cond}} = \overline{R_{\text{ds(on)}}(P_{\text{total}})} \cdot I_{\text{rms}}^2$ 

Switching energies follow from switching frequency

$$P_{\rm sw} = P_{\rm total} - P_{\rm cond}$$

$$E_{\rm sw} = E_{\rm on} + E_{\rm off} = \frac{P_{\rm sw}}{f_{\rm s}}$$
 (for CCM)

Half-bridge switching energy dissipation per switching period

#### **Soft-Switching Losses**

- $E_{sw} = 2E_{off}$  for TCM
- Direct & accurate measurement of residual soft-switching losses!

## **TT Bridge-Leg Switching Loss Characterization: Method (1)**

• Different device types (SiC, M-BDS) require loss separation: measure individual case temperatures ( $T_{S1,H}$ ,  $T_{S1,M}$ ,  $T_{S1,L}$ ) and  $T_{HS}$ 



- Thermal network with 11 parameters
- Calibration with DC power injection & particle swarm fit (MATLAB)

#### **Calibration Example**



 Note: initial, fast transient ignored (therm. cap. of switches, PCB, heat spreaders, etc.)



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## TT Bridge-Leg Switching Loss Characterization: Method (2)

Different device types (SiC, M-BDS) require loss separation: measure individual case temperatures (T<sub>S1,H</sub>, T<sub>S1,M</sub>, T<sub>S1,L</sub>) and T<sub>HS</sub>



**Direct to** 

ambient

Cross

couplings

 Calibration with DC power injection & particle swarm fit (MATLAB)

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To heat sink

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## **TT Bridge-Leg Switching Loss Characterization: Results**

#### **Calibration Data / Accuracy**

Injected DC power vs. calorimetric measurement



#### Measured Hard- and Soft-Switching Losses







## Performance Evaluation of TT Main Converter Stage: CCM Designs





### **Specifications / Modeling**

- T<sub>i</sub> = 125 °C, T<sub>amb</sub> = 45 °C / heat sink volume: CSPI = 15 W/(dm<sup>3</sup>K)
- $\Delta i_{\text{LF,pp}} = 30 \%$  (CCM),  $\Delta v_{\text{CF,pp}} = 2 \%$ ,
- Pareto-optimal inductor designs (N87 or KoolMu)
- Inverter or rectifier designs with  $\cos\phi = \pm 1$





F. Vollmaier, N. Nain, J. Huber, J. W. Kolar, K. K. Leong, and B. Pandya, "Performance evaluation of future T-Type PFC rectifier and inverter systems with monolithic bidirectional 600 V GaN switches."



Time (p.u.)



## Performance Evaluation of TT Main Converter Stage: TCM Designs

#### **TT Main Converter Stage**



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- $\Delta i_{\text{LF,pp}} = 30 \%$  (CCM),  $\Delta v_{\text{CF,pp}} = 2 \%$ ,
- Pareto-optimal inductor designs (N87 or KoolMu)
- Inverter or rectifier designs with  $\cos\phi = \pm 1$



 TCM favorable for lower design powers, e.g., 1 kW



#### Further Details => Paper @ ECCE USA 2021

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# **AC/AC Current-Source Converters with M-BDSs**





## **M-BDS Commutation Cell for AC-AC CSC and DMC**

AC-AC Current-Source Converter (CSC)



AC-AC Direct Matrix Converter (DMC)



#### ► 4 x Basic Commutation Cell

► 3 x Basic Commutation Cell







## **M-BDS Commutation Cell Test PCB: Commutation Loops**

Commutation voltages: line-to-line AC voltages / Commutation capacitors: two AC-side filter capacitors



Note: approximate loops only (partly vertical)







## **Remark:** Passive Toggling of Commutation Cell's 3<sup>rd</sup> Switch

Three switches connected to common switch node / Example: Commutation from S<sub>1</sub> to S<sub>2</sub>



![](_page_27_Picture_5.jpeg)

![](_page_28_Picture_1.jpeg)

### **M-BDS Commutation Cell Test PCB: Half-Bridge Configuration**

![](_page_28_Figure_3.jpeg)

![](_page_28_Picture_4.jpeg)

![](_page_29_Picture_0.jpeg)

![](_page_29_Picture_1.jpeg)

## **Remark: 4-Step Commutation (Positive Current)**

Ensure current path & avoid DC voltage short-circuit / Current-direction dependent gating sequence (pos. current shown)

![](_page_29_Figure_4.jpeg)

![](_page_29_Figure_5.jpeg)

![](_page_29_Picture_6.jpeg)

![](_page_30_Picture_0.jpeg)

![](_page_30_Picture_1.jpeg)

## **Remark: 4-Step Commutation (Negative Current)**

> Ensure current path & avoid DC voltage short-circuit / Current-direction dependent gating sequence (neg. current shown)

![](_page_30_Figure_4.jpeg)

![](_page_30_Picture_5.jpeg)

![](_page_31_Picture_1.jpeg)

## Continuous M-BDS Half-Bridge Operation at ± 400 V

![](_page_31_Figure_3.jpeg)

![](_page_31_Picture_4.jpeg)

![](_page_32_Picture_0.jpeg)

![](_page_32_Picture_1.jpeg)

## **M-BDS Half-Bridge Switching Loss Characterization**

Transient calorimetric method / 4-Step commutation sequence / All four quadrants / Two voltage levels (CSC)

![](_page_32_Figure_4.jpeg)

Note: Preliminary results / Gate setup & timings not yet fully optimized => Lower switching losses achievable

![](_page_32_Picture_6.jpeg)

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![](_page_33_Picture_1.jpeg)

## Performance of AC-AC CSC with 600 V / 140 m $\Omega$ GaN M-BDSs

Motor drives for aircraft applications

![](_page_33_Figure_4.jpeg)

#### Specifications / Modeling

- 115 V rms, 400 Hz grid
- 92 V rms, 600 Hz, 1 kW output (design point)
- T<sub>j</sub> = 100 °C, T<sub>amb</sub> = 45 °C / heat sink volume: CSPI = 15 W/(dm<sup>3</sup>K)
- $\Delta i_{Ldc,pp} = 10 \%$  (peak-to-peak),  $\Delta Q_{CF} = 5 \%$
- Pareto-optimal inductor designs (N87 or KoolMu)

![](_page_33_Figure_11.jpeg)

 Performance evaluation based on measured M-BDS switching losses

![](_page_33_Figure_13.jpeg)

Note: Preliminary results / Work in progress!

![](_page_33_Picture_15.jpeg)

![](_page_34_Picture_0.jpeg)

![](_page_34_Picture_1.jpeg)

# **Conclusion & Outlook**

![](_page_34_Picture_3.jpeg)

![](_page_35_Picture_0.jpeg)

![](_page_35_Picture_1.jpeg)

### **Conclusion & Outlook**

- **600** V / 140 mΩ (infineon GaN M-BDS continuous operation at  $\pm$  400 V
- Calorimetric switching loss characterization of M-BDS in GaN/SiC TT bridge-leg and all-GaN CSC commutation cell

![](_page_35_Picture_5.jpeg)

#### **TT DC-AC Converter**

#### **Current-Source AC-AC Converter**

![](_page_35_Figure_8.jpeg)

- **Full prototypes** under development / System-level experimental performance verification
- ► GaN M-BDS technology takes flight and promises straightforward designs and superior performance

![](_page_35_Picture_11.jpeg)

![](_page_36_Picture_0.jpeg)

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## **Thank You!**

![](_page_36_Picture_3.jpeg)

![](_page_36_Picture_4.jpeg)